

# flowStats

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autoGate	<i>Automated gating of single populations in 2D</i>
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### Description

This function tries to fit a single `norm2Filter` based on a rough preselection of the data. This function is considered internal. Please use the API provided by [lymphGate](#).

### Usage

```
autoGate(x, ..., scale = 2.5)
```

### Arguments

x	An object of class <code>flowSet</code>
...	Named arguments or a list of the ranges used for the initial rough preselection. This gets passed on to <code>rectangleGate</code> , see it's documentation for details.
scale	The scale parameter that gets passed on to <code>norm2Filter</code> .

**Details**

The flowSet is first filtered using a `rectangleGate` and the `norm2Filter` is subsequently fitted to the remaining subset.

**Value**

A list with items:

`x`                   The filtered flowSet.  
`n2gate`             The `norm2Filter` object.  
`n2gateResults`     The `filterResult` after applying the `norm2Filter` on the flowSet.

**Author(s)**

Florian Hahne

**See Also**

[lymphGate](#), [norm2Filter](#)

**Examples**

```
data(GvHD)
flowStats:::autoGate(GvHD[10:15], "FSC-H"=c(100,500), "SSC-H"=c(0, 400))
```

---

binByRef

*Bin a test data set using bins previously created by probability binning a control dataset*

---

**Description**

The bins generated by probability binning a control data set can be applied to a test data set to perform statistical comparisons by methods such as the Chi-squared test or the probability binning statistic.

**Usage**

```
binByRef(binRes, data)
```

**Arguments**

`binRes`            The result generated by calling the `probBin` function on a control dataset.  
`data`              An object of class `flowFrame`

**Value**

An environment containing the matrices for each bin of the test data set

**Author(s)**

Nishant Gopalakrishnan

**See Also**

[plotBins](#), [proBin](#)

**Examples**

```
data(GvHD)
resCtrl<-proBin(GvHD[[1]],200)
resSample<-binByRef(resCtrl,GvHD[[2]])
ls(resSample)
```

---

calcPBChiSquare	<i>Probability binning metric for comparing the probability binned datasets</i>
-----------------	---

---

**Description**

This function calculates the Probability binning metric proposed by Baggerly et al. The function utilizes the data binned using the `proBin` and `binByRef` functions.

**Usage**

```
calcPBChiSquare(ctrlRes, sampRes, ctrlCount, sampCount)
```

**Arguments**

<code>ctrlRes</code>	The result generated by calling the <code>proBin</code> function on a control dataset.
<code>sampRes</code>	The result generated by calling the <code>binByRef</code> function on a test sample dataset
<code>ctrlCount</code>	The number of events in the control sample
<code>sampCount</code>	The number of events in the test sample being compared

**Value**

A list containing the statistic, p.value, observed, expected counts and the residuals

**Author(s)**

Nishant Gopalakrishnan

**See Also**

[proBin](#), [calcPBChiSquare](#)

**Examples**

```

data(GvHD)
# flow frame 1 is treated as control dataset and used to generate bins
resCtrl<-proBin(GvHD[[1]][,c("FSC-H", "SSC-H", "Time")],200)
plotBins(resCtrl,GvHD[[1]],channels=c("FSC-H", "SSC-H", "Time"),title="Binned control data")
# Same bins are applied to flowFrame 16
resSample<-binByRef(resCtrl,GvHD[[16]][,c("FSC-H", "SSC-H", "Time")])
ctrlCount<-nrow(GvHD[[1]])
sampCount<-nrow(GvHD[[16]])
stat<-calcPBChiSquare(resCtrl,resSample,ctrlCount,sampCount)

```

---

calcPearsonChi	<i>Pearsons chi-square statistic for comparing the probability binned datasets</i>
----------------	--

---

**Description**

This function calculates the Pearsons chi-squared statistic for comparing data binned using the `proBin` and `binByRef` functions. Internally, the function utilizes the `chisq.test` function.

**Usage**

```
calcPearsonChi(ctrlRes, sampRes)
```

**Arguments**

ctrlRes	The result generated by calling the <code>proBin</code> function on a control dataset.
sampRes	The result generated by calling the <code>binByRef</code> function on a sample dataset

**Value**

A list containing the statistic, p.value, observed, expected counts and the residuals

**Author(s)**

Nishant Gopalakrishnan

**See Also**

[proBin](#), [calcPBChiSquare](#)

**Examples**

```

data(GvHD)
# flow frame 1 is treated as control dataset and used to generate bins
resCtrl<-proBin(GvHD[[1]][,c("FSC-H", "SSC-H", "Time")],200)
plotBins(resCtrl,GvHD[[1]],channels=c("FSC-H", "SSC-H", "Time"),title="Binned control data")
# Same bins are applied to flowFrame 16
resSample<-binByRef(resCtrl,GvHD[[16]][,c("FSC-H", "SSC-H", "Time")])
stat<-calcPearsonChi(resCtrl,resSample)

```

---

curvPeaks *Parse curv1Filter output*

---

### Description

Parse the output of `curv1Filter` and find modes and midpoints of the high-density regions. This function is considered to be internal.

### Usage

```
curvPeaks(x, dat, borderQuant = 0.01, n = 201, from, to, densities=NULL)
```

### Arguments

<code>x</code>	A <code>multipleFilterResult</code> produced by a <code>curv1Filter</code> operation.
<code>dat</code>	The corresponding <code>flowFrame</code> .
<code>borderQuant</code>	A numeric in $[0, 1]$ giving the extreme quantiles for which high-density regions are ignored.
<code>n, from, to</code>	Arguments are passed on to <code>density</code> .
<code>densities</code>	The optional y values of the density estimate computed for the respective data.

### Value

A list with items

<code>peaks</code>	x and y locations of the modes of the regions in the density estimates.
<code>regions</code>	the left and right margins of the regions.
<code>midpoints</code>	the mean of regions.
<code>regPoints</code>	x and y locations of the outline of the significant density regions.
<code>densFuns</code>	an approximation function of the density estimate

### Author(s)

Florian Hahne

### See Also

[landmarkMatrix](#)

### Examples

```
data(GvHD)
tmp <- filter(GvHD[[10]], curv1Filter("FSC-H"))
res <- flowStats:::curvPeaks(tmp, exprs(GvHD[[10]])[, "FSC-H"])
```

---

density1d	<i>Find most likely separation between positive and negative populations in 1D</i>
-----------	--

---

### Description

The function tries to find a reasonable split point between the two hypothetical cell populations "positive" and "negative". This function is considered internal, please use the API provided by [rangeGate](#).

### Usage

```
density1d(x, stain, alpha = "min", sd = 2, plot = FALSE, borderQuant = 0.1, absolute = TRUE, inBetween = FALSE, ...)
```

### Arguments

x	A <a href="#">flowSet</a> or <a href="#">flowFrame</a> .
stain	A character scalar giving the flow parameter for which to compute the separation.
alpha	A tuning parameter that controls the location of the split point between the two populations. This has to be a numeric in the range $[0, 1]$ , where values closer to 0 will shift the split point closer to the negative population and values closer to 1 will shift towards the positive population. Additionally, the value of <code>alpha</code> can be "min", in which case the split point will be selected as the area of lowest local density between the two populations.
sd	For the case where there is only a single population, the algorithm falls back to estimating the mode of this population and a robust measure of the variance of its distribution. The <code>sd</code> tuning parameter controls how far away from the mode the split point is set.
plot	Create a plot of the results of the computation.
borderQuant	Usually the instrument is set up in a way that the positive population is somewhere on the high end of the measurement range and the negative population is on the low end. This parameter allows to disregard populations with mean values in the extreme quantiles of the data range. Its value should be in the range $[0, 1]$ .
absolute	Logical controlling whether to classify a population (positive or negative) relative to the theoretical measurement range of the instrument or the actual range of the data. This can be set to <code>TRUE</code> if the alignment of the measurement range is not optimal and the bulk of the data is on one end of the theoretical range.
inBetween	Force the algorithm to put the separator in between two peaks. If there are more than two peaks, this argument is ignored.
...	Further arguments.

### Details

The algorithm first tries to identify high density regions in the data. If the input is a `flowSet`, density regions will be computed on the collapsed data, hence it should have been normalized before (see [warpSet](#) for one possible normalization technique). The high density regions are

then classified as positive and negative populations, based on their mean value in the theoretical (or absolute if argument `absolute=TRUE`) measurement range. In case there are only two high-density regions the lower one is usually classified as the negative populations, however the heuristics in the algorithm will force the classification towards a positive population if the mean value is already very high. The `absolute` and `borderQuant` arguments can be used to control this behaviour. The split point between populations will be drawn at the value of minimum local density between the two populations, or, if the `alpha` argument is used, somewhere between the two populations where the value of alpha forces the point to be closer to the negative ( $0 - 0.5$ ) or closer to the positive population ( $0.5 - 1$ ).

If there is only a single high-density region, the algorithm will fall back to estimating the mode of the distribution ([hubers](#)) and a robust measure of it's variance and, in combination with the `sd` argument, set the split point somewhere in the right or left tail, depending on the classification of the region.

For more than two populations, the algorithm will still classify each population into positive and negative and compute the split point between those clusters, similar to the two population case.

### Value

A numeric indicating the split point between positive and negative populations.

### Author(s)

Florian Hahne

### See Also

[warpSet](#), [rangeGate](#)

### Examples

```
data(GvHD)
dat <- GvHD[pData(GvHD)$Patient==10]
dat <- transform(dat, "FL4-H"=asinh(`FL4-H`), "FL3-H"=asinh(`FL3-H`))
d <- flowStats::density1d(dat, "FL4-H", plot=TRUE)
if(require(flowViz))
densityplot(~`FL4-H`, dat, reflines=d)

## tweaking the location
flowStats::density1d(dat, "FL4-H", plot=TRUE, alpha=0.8)

## only a single population
flowStats::density1d(dat, "FL3-H", plot=TRUE)
flowStats::density1d(dat, "FL3-H", plot=TRUE, sd=2)
```

---

flowStats-package *Statistical methods for flow cytometry data analysis*

---

### Description

Functions, methods and classes implementing algorithms for statistical analysis of flow cytometry data. This involves mostly data normalization and automated gating.

**Details**

Package: flowStats  
Type: Package  
Version: 1.0  
License: Artistic-2.0  
Lazyload: yes

**Author(s)**

Florian Hahne

Maintainer: Florian Hahne <fhahne@fhcrc.org>

---

ITN

*Sample flow cytometry data*

---

**Description**

A `flowSet` containing data from 15 patients.

**Usage**

```
data(ITN)
```

**Format**

A `flowSet` containing 15 `flowFrames`. There are 3 patient groups with 5 samples each.

**Source**

Immune Tolerance Network

---

landmarkMatrix

*Compute and cluster high density regions in 1D*

---

**Description**

This functions first identifies high-density regions for each `flowFrame` in a `flowSet` and subsequently tries to cluster these regions, yielding the landmarks matrix that needs to be supplied to `landmarkreg`. The function is considered to be internal.

**Usage**

```
landmarkMatrix(data, fres, parm, border=0.05, peakNr=NULL, densities = NULL, n =
```



**Arguments**

data	A flowSet.
fres	A list of <code>filterResultList</code> objects generated by a filtering operation using a <code>curv1Filter</code> . Each list item represents the results for one of the flow parameters in <code>parm</code> .
parm	Character scalar of flow parameter to compute landmarks for.
border	A numeric in $[0, 1]$ . Ignore all high-density regions with mean values in the extreme percentiles of the data range.
peakNr	Force a fixed number of peaks.
densities	An optional matrix of y values of the density estimates for the flowSet. If this is not present, density estimates will be calculated by the function.
n	Number of bins used for the density estimation.

**Details**

In order to normalize the data using the `landmarkreg` function in the `fda`, a set of landmarks has to be computed for each `flowFrame` in a `flowSet`. The number of landmarks has to be the same for each frame. This function identifies high-density regions in each frame, computes a simple clustering and returns a matrix of landmark locations. Missing landmarks of individual frames are substituted by the mean landmark location of the respective cluster.

**Value**

A matrix of landmark locations. Columns are landmarks and rows are `flowFrames`.

**Author(s)**

Florian Hahne

**See Also**

[landmarkreg](#), [warpSet](#)

**Examples**

```
data(GvHD)
tmp <- list("FSC-H"=filter(GvHD[1:3], curv1Filter("FSC-H")))
res <- flowStats:::landmarkMatrix(GvHD[1:3], tmp, "FSC-H")
```

---

lymphFilter-class *Automated gating of elliptical cell populations in 2D.*

---

**Description**

Cell populations of roughly elliptical shape in two-dimensional projections are of huge interest in many flow cytometry applications. This function identifies a single such population, potentially from a mixture of multiple populations.

**Usage**

```
lymphGate(x, channels, preselection=NULL, scale=2.5,
          bwFac=1.3, filterId="defaultLymphGate", evaluate=TRUE, ...)

lymphFilter(channels, preselection=as.character(NULL),
            scale=2.5, bwFac=1.3, filterId="defaultLymphFilter")
```

**Arguments**

<code>x</code>	An object of class <code>flowSet</code> .
<code>channels</code>	A character vector of length 2 of valid flow parameters in <code>x</code> .
<code>preselection</code>	Either <code>NULL</code> , in which case this boils down to fitting a regular <code>norm2Filter</code> , a character scalar giving one of the flow parameters in <code>x</code> , or a named list of numerics specifying the initial rough preselection. The latter gets passed on to <code>rectangleGate</code> , see its documentation for details.
<code>scale</code>	The <code>scaleFactor</code> parameter that gets passed on to <code>norm2Filter</code> .
<code>bwFac</code>	The bandwidth factor that gets passed on to <code>curv1Filter</code> .
<code>filterId</code>	A character used as <code>filterId</code> .
<code>evaluate</code>	A logical indicating whether the filter should be resolved (computation of the <code>filterResult</code> and the subset).
<code>...</code>	Additional arguments.

**Details**

This algorithm does not apply real mixture modelling, however it is able to identify a single elliptical cell population from a mixture of multiple such populations. The idea is to first define a rough rectangular preselection and, in a second step, fit a bivariate normal distribution to this subset only. Depending on the value of `preselection`, the initial rough selection is either

**NULL:** No preselection at all

**character scalar** Preselection based on cells that are positive for a single marker only. This allows for back-gating, for instances by selecting CD4+ T-cells and using this information to back-gate lymphocytes in FSC and SSC. Positive cells are identified using a `curv1Filter`.

**a named list of numerics:** Preselection by a rectangular gate. The items of the list have to be numerics of length one giving the gate boundaries in the respective dimensions.

The `lymphFilter` class and constructor provide the means to treat `lymphGates` as regular `flowCore` filters.

**Value**

A list with items

<code>x</code>	The filtered <code>flowSet</code> .
<code>n2gate</code>	The <code>norm2Filter</code> object.
<code>n2gateResults</code>	The <code>filterResult</code> after applying the <code>norm2Filter</code> on the <code>flowSet</code> .

for the `lymphGate` function. Note that `x` and `n2gateResults` are `NULL` when `eval=FALSE`.

The `lymphFilter` constructor returns an object of class `lymphFilter`, which can be used as a regular `flowCore` filter.

**Extends**

Class `"parameterFilter"`, directly.

Class `"concreteFilter"`, by class `"parameterFilter"`, distance 2.

Class `"filter"`, by class `"parameterFilter"`, distance 3.

**Slots**

See Arguments section for details.

**preselection:** Object of class `character`, the name of the flow parameter used for preselection.

**rectDef:** Object of class `list`, the initial rectangular selection.

**scale:** Object of class `numeric`.

**bwFac:** Object of class `numeric`.

**parameters:** Object of class `parameters`, the flow parameters to operate on.

**filterId:** Object of class `"character"`, the filter identifier.

**Objects from the Class**

Objects can be created by calls of the form `new("lymphFilter", parameters, ...)` or using the constructor `lymphFilter`. The constructor is the recommended way of object instantiation.

**Methods**

**%in%** signature(`x = "flowFrame"`, `table = "lymphFilter"`): the work horse for doing the actual filtering. Internally, this simply calls the `lymphGate` function.

**Author(s)**

Florian Hahne

**See Also**

`norm2Filter`, `curv1Filter`

**Examples**

```
data(GvHD)
dat <- GvHD[pData(GvHD)$Patient==10]
dat <- transform(dat, "FL4-H"=asinh(`FL4-H`))
lg <- lymphGate(dat, channels=c("FSC-H", "SSC-H"), preselection="FL4-H", scale=1.5)

if(require(flowViz))
xyplot(`SSC-H`~`FSC-H`, dat, filter=lg$n2gate)

## This is using the abstract lymphFilter class instead
lf <- lymphFilter(channels=c("FSC-H", "SSC-H"), preselection="FL4-H")
filter(dat, lf)
```

---

plotBins

*Plots the probability bins overlaid with flowFrame data*


---

### Description

This function is useful in visualizing the differences between the binned control and sample datasets. The bins generated from the control dataset are overlaid with the sample dataset. An optional argument residuals can be used to shade each bin based on a calculated statistical measure of difference between the number of events in each bin.

### Usage

```
plotBins(binRes, data, channels, title, residuals, shadeFactor)
```

### Arguments

binRes	The result generated by calling the <code>probBin</code> function on a control dataset.
data	An object of class <code>flowFrame</code> <code>sample(dataset)</code>
channels	The flow parameters to be plotted. In cases where more than two parameters are binned from the control set, the <code>plotBins</code> function plots the projections of the hyperplanes in 2 dimensions)
title	Optional title for the plot generated
residuals	A vector of length equal to the number of bins generated that can be used to shade each bin. The residuals from the <code>calcPearsonChi</code> function or the <code>calcPBChiSquare</code> function can be used to highlight the bins that are different between control and sample datasets
shadeFactor	Optional argument between 0 and 1 that controls the intensity of the shading of bins

### Author(s)

Nishant Gopalakrishnan

### See Also

[proBin](#), [calcPearsonChi](#), [calcPBChiSquare](#)

### Examples

```
data(GvHD)
# flow frame 1 is treated as control dataset and used to generate bins
resCtrl<-proBin(GvHD[[1]][,c("FSC-H", "SSC-H", "Time")],200)
plotBins(resCtrl,GvHD[[1]],channels=c("FSC-H", "SSC-H"),title="Binned control data")
# Same bins are applied to flowFrame 16
resSample<-binByRef(resCtrl,GvHD[[16]][,c("FSC-H", "SSC-H", "Time")])
stat<-calcPearsonChi(resCtrl,resSample)
dev.new()
plotBins(resCtrl,data=GvHD[[16]],channels=c("FSC-H", "SSC-H", "Time"),title="Comparision 1
residuals=stat$residuals[2,],shadeFactor=0.7)
```

---

 proBin
 

---

*Probability binning - a metric for evaluating multivariate differences*


---

### Description

This function divides the flowframe events into bins such that each bin contains the same number of events. The number of events falling into each bin can then be compared across the control and test samples using statistical methods such as the Chi-squared test.

### Usage

```
proBin(m, minEvents)
```

### Arguments

m	An object of class <code>flowFrame</code>
minEvents	The <code>minEvents</code> The minimum number of events in each bin. (i.e. the termination criterion for the probability binning algorithm)

### Details

The `flowSet` is first filtered using a `rectangleGate` and the `norm2Filter` is subsequently fitted to the remaining subset.

### Value

A list with items:

table	<p>A <code>data.frame</code> that stores information regarding each node of the tree generated during each stage of the probability binning algorithm. Each row in the table represents a node, the first row representing the original <code>flowFrame</code> matrix.</p> <p>The <code>dataIdx</code> column provides indexes for retrieving the matrices during each stage of the binning process from the environment <code>data</code>.</p> <p>The <code>parent</code> field indicates the row number in the table that holds the parent information for the corresponding node.</p> <p>The <code>left</code> and <code>right</code> columns indicates the row numbers in the table that stores information regarding the children of that particular node. The leaf nodes that hold the binned data can be identified by the nodes with the left or right values of zero( ie. no children nodes)</p> <p>The <code>visited</code> column is used internally by the algorithm to check if a particular node has been visited during the computation process.</p>
data	<p>An environment in which the matrices generated during each stage of the probability binning process is stored. The matrices stored at the leaf nodes represent the binned events obtained after the stop criterion of <code>minEvents</code> has been achieved. These can be identified by the corresponding <code>dataIdx</code> fields provided by the rows in the table with the left or right column values of zero.</p>
limits	<p>A list containing the the boundaries of each hyperplane generated during probability binning</p>

`splitPars` A `data.frame` containing two columns `splitCol` - indicates the column number of the `flowFrame`, the split was performed.  
`splitMed` - The median value which was used as the threshold for splitting the `flowFrame`  
 The `splitCol` and `splitMed` parameters are utilized by the `plotBins` and `shadeBins` functions in visualizing the differences between control and test sample cases.

**Author(s)**

Nishant Gopalakrishnan

**See Also**

[plotBins](#), [binByRef](#)

**Examples**

```
data(GvHD)
res<-proBin(GvHD[[1]],200)
```

---

quadrantGate      *Automated quad gating*

---

**Description**

This function tries to find the most likely separation of two-dimensional flow cytometry in four quadrants.

**Usage**

```
quadrantGate(x, stains, alpha=c("min", "min"), sd=c(2, 2), plot=FALSE,
  filterId="defaultQuadGate", ...)
```

**Arguments**

<code>x</code>	A <a href="#">flowSet</a> or <a href="#">flowFrame</a> .
<code>stains</code>	A character vector of length two giving the two flow parameters for which the quad gate is to be computed.
<code>alpha, sd</code>	Tuning factors to control the computation of the gate boundaries. See <a href="#">rangeGate</a> for details.
<code>plot</code>	Logical. Produce plots of intermediate results.
<code>filterId</code>	Character, the name assigned to the resulting filter.
<code>...</code>	Additional arguments

## Details

The most likely separation between positive and negative stains for two-dimensional data is computed based on density estimates. Essentially, the gate parameters are first fitted separately for the two parameters and later combined. See the documentation for [rangeGate](#) for details. There is a certain amount of heuristics involved in this process. The algorithm can be slightly tweaked using the `alpha` and `sd` arguments. Their values will be recycled for the two dimensions unless explicitly given as vectors of length 2.

## Value

An object of class [quadGate](#).

## Author(s)

Florian Hahne

## See Also

[quadGate](#), [rangeGate](#)

## Examples

```
data(GvHD)
dat <- GvHD[pData(GvHD)$Patient==10]
dat <- transform(dat, "FL4-H"=asinh(`FL4-H`), "FL2-H"=asinh(`FL2-H`))
qq <- quadrantGate(dat, c("FL2-H", "FL4-H"))
qq
if(require(flowViz))
xyplot(`FL2-H`~`FL4-H`, dat, filter=qq)
qq <- quadrantGate(dat, c("FL2-H", "FL4-H"), alpha=c(0.1, 0.9), plot=TRUE)
```

---

rangeGate

*Find most likely separation between positive and negative populations in 1D*

---

## Description

The function tries to find a reasonable split point between the two hypothetical cell populations "positive" and "negative".

## Usage

```
rangeGate(x, stain, alpha="min", sd=2, plot=FALSE, borderQuant=0.1,
absolute=TRUE, filterId="defaultRectangleGate", positive=TRUE, ...)
```

**Arguments**

<code>x</code>	A <code>flowSet</code> or <code>flowFrame</code> .
<code>stain</code>	A character scalar giving the flow parameter for which to compute the separation.
<code>alpha</code>	A tuning parameter that controls the location of the split point between the two populations. This has to be a numeric in the range $[0, 1]$ , where values closer to 0 will shift the split point closer to the negative population and values closer to 1 will shift towards the positive population. Additionally, the value of <code>alpha</code> can be "min", in which case the split point will be selected as the area of lowest local density between the two populations.
<code>sd</code>	For the case where there is only a single population, the algorithm falls back to estimating the mode of this population and a robust measure of the variance of its distribution. The <code>sd</code> tuning parameter controls how far away from the mode the split point is set.
<code>plot</code>	Create a plot of the results of the computation.
<code>borderQuant</code>	Usually the instrument is set up in a way that the positive population is somewhere on the high end of the measurement range and the negative population is on the low end. This parameter allows to disregard populations with mean values in the extreme quantiles of the data range. Its value should be in the range $[0, 1]$ .
<code>absolute</code>	Logical controlling whether to classify a population (positive or negative) relative to the theoretical measurement range of the instrument or the actual range of the data. This can be set to <code>TRUE</code> if the alignment of the measurement range is not optimal and the bulk of the data is on one end of the theoretical range.
<code>filterId</code>	Character, the name assigned to the resulting filter.
<code>positive</code>	Create a range gate that includes the positive ( <code>TRUE</code> ) or the negative ( <code>FALSE</code> ) population.
<code>...</code>	Further arguments.

**Details**

The algorithm first tries to identify high density regions in the data. If the input is a `flowSet`, density regions will be computed on the collapsed data, hence it should have been normalized before (see `warpSet` for one possible normalization technique). The high density regions are then classified as positive and negative populations, based on their mean value in the theoretical (or `absolute` if argument `absolute=TRUE`) measurement range. In case there are only two high-density regions the lower one is usually classified as the negative population, however the heuristics in the algorithm will force the classification towards a positive population if the mean value is already very high. The `absolute` and `borderQuant` arguments can be used to control this behaviour. The split point between populations will be drawn at the value of minimum local density between the two populations, or, if the `alpha` argument is used, somewhere between the two populations where the value of `alpha` forces the point to be closer to the negative ( $0 - 0.5$ ) or closer to the positive population ( $0.5 - 1$ ).

If there is only a single high-density region, the algorithm will fall back to estimating the mode of the distribution (`hubers`) and a robust measure of its variance and, in combination with the `sd` argument, set the split point somewhere in the right or left tail, depending on the classification of the region.

For more than two populations, the algorithm will still classify each population into positive and negative and compute the split point between those clusters, similar to the two population case.



**Value**

A range gate, more explicitly an object of class `rectangelGate`.

**Author(s)**

Florian Hahne

**See Also**

`warpSet`, `rangeGate`, `rectangelGate`

**Examples**

```
data(GvHD)
dat <- GvHD[pData(GvHD)$Patient==10]
dat <- transform(dat, "FL4-H"=asinh(`FL4-H`), "FL3-H"=asinh(`FL3-H`))
rg <- rangeGate(dat, "FL4-H", plot=TRUE)
rg
```

---

warpSet

*Normalization based on landmark registration*


---

**Description**

This function will perform a normalization of flow cytometry data based on warping functions computed on high-density region landmarks for individual flow channels.

**Usage**

```
warpSet(x, stains, grouping = NULL, monwrld = TRUE, subsample=NULL,
peakNr=NULL, clipRange=0.01, nbreaks=11, fres, ...)
```

**Arguments**

<code>x</code>	A <code>flowSet</code> .
<code>stains</code>	A character vector of flow parameters in <code>x</code> to be normalized.
<code>grouping</code>	A character indicating one of the phenotypic variables in the <code>phenoData</code> slot of <code>x</code> used as a grouping factor. The within-group and between-group variance is computed and a warning is issued in case the latter is bigger than the former, indicating the likely removal of signal by the normalization procedure.
<code>monwrld</code>	Logical. Compute strictly monotone warping functions. This gets directly passed on to <code>landmarkreg</code> .
<code>subsample</code>	Numeric. Reduce the number of events in each <code>flowSet</code> by sub sampling for all density estimation steps and the calculation of the warping functions. This can increase computation time for large data sets, however it might reduce the accuracy of the density estimates. To be used with care.
<code>peakNr</code>	Numeric scalar. Force a fixed number of peaks to use for the normalization.

<code>clipRange</code>	Only use peaks within a clipped data range. Essentially, the number indicates the percent of clipping on both sides of the data range, e.g. $\min(x) - 0.01 * \text{diff}(\text{range}(x))$ .
<code>nbreaks</code>	The number of spline sections used to approximate the data. Higher values produce more accurate results, however this comes with the cost of increased computing times. For most data, the default setting is good enough.
<code>fres</code>	A named list of <code>filterResultList</code> objects. This can be used to speed up the process since the <code>curv1Filter</code> step can take quite some time.
<code>...</code>	Further arguments that are passed on to <code>landmarkreg</code> .

### Details

Normalization is achieved by first identifying high-density regions (landmarks) for each `flowFrame` in the `flowSet` for a single channel and subsequently by computing warping functions for each `flowFrame` that best align these landmarks. This is based on the algorithm implemented in the `landmarkreg` function in the `fda` package. An intermediate step classifies the high-density regions, see `landmarkMatrix` for details.

Please note that this normalization is on a channel-by-channel basis. Multiple channels are normalized in a loop.

### Value

The normalized `flowSet`.

### Note

We currently use a patched `fda` version.

### Author(s)

Florian Hahne

### References

J.O. Ramsay and B.W. Silverman: Applied Functional Data Analysis, Springer 2002

### See Also

`curv1Filter`, `landmarkMatrix`

### Examples

```
data(ITN)
dat <- transform(ITN, "CD4"=asinh(CD4), "CD3"=asinh(CD3), "CD8"=asinh(CD8))
lg <- lymphGate(dat, channels=c("CD3", "SSC"),
preselection="CD4", scale=1.5)
dat <- Subset(dat, lg$n2gate)
datr <- warpSet(dat, "CD8", grouping="GroupID", monwrdr=TRUE)
if(require(flowViz)){
d1 <- densityplot(~CD8, dat, main="original", filter=curv1Filter("CD8"))
d2 <- densityplot(~CD8, datr, main="normalized", filter=curv1Filter("CD8"))
plot(d1, split=c(1,1,2,1))
plot(d2, split=c(2,1,2,1), newpage=FALSE)
```

*warpSet*

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}

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