

# Package ‘visiumStitched’

October 2, 2025

**Title** Enable downstream analysis of Visium capture areas stitched together with Fiji

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**Description** This package provides helper functions for working with multiple Visium capture areas that overlap each other. This package was developed along with the companion example use case data available from [https://github.com/LieberInstitute/visiumStitched\\_brain](https://github.com/LieberInstitute/visiumStitched_brain). visiumStitched prepares SpaceRanger (10x Genomics) output files so you can stitch the images from groups of capture areas together with Fiji. Then visiumStitched builds a SpatialExperiment object with the stitched data and makes an artificial hexagonal grid enabling the seamless use of spatial clustering methods that rely on such grid to identify neighboring spots, such as PRECAST and BayesSpace. The SpatialExperiment objects created by visiumStitched are compatible with spatialLIBD, which can be used to build interactive websites for stitched SpatialExperiment objects. visiumStitched also enables casting SpatialExperiment objects as Seurat objects.

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.add_error_metrics	<i>Add error metrics related to array-coordinate mapping</i>
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Description

Given tibble(s) before and after mapping to new array coordinates, calculate metrics related to the suitability of the mapping.

Usage

.add\_error\_metrics(coords, coords\_new, inter\_spot\_dist\_px)

**Arguments**

<code>coords</code>	A <code>tibble()</code> containing <code>array_row</code> , <code>array_col</code> , <code>key</code> , <code>pxl_col_in_fullres</code> , <code>pxl_row_in_fullres</code> , <code>pxl_col_in_fullres_rounded</code> , <code>pxl_row_in_fullres_rounded</code> , and <code>capture_area</code> columns, representing data before mapping to new array coordinates for one group.
<code>coords_new</code>	A <code>tibble()</code> containing <code>array_row</code> , <code>array_col</code> , <code>key</code> , <code>pxl_col_in_fullres</code> , <code>pxl_row_in_fullres</code> , <code>pxl_col_in_fullres_rounded</code> , and <code>pxl_row_in_fullres_rounded</code> columns, representing data after mapping to new array coordinates for one group.
<code>inter_spot_dist_px</code>	A <code>numeric(1)</code> giving the number of pixels between spots for the group.

**Details**

Add column `shared_neighbors`, the fraction of neighbors a spot started with that are retained after mapping; add column `euclidean_error`, the number of multiples of the inter-spot distance a spot must move to be placed in the new array coordinates.

**Value**

A `tibble()` copy of `coords_new` with additional `shared_neighbors` and `euclidean_error` columns.

**Author(s)**

Nicholas J. Eagles

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`.clean_round`*Round to the nearest integer, always rounding up at 0.5*

---

**Description**

This consistent behavior is favorable for our application, where we want to minimize duplicate mappings of spots to new array coordinates.

**Usage**

```
.clean_round(x)
```

**Arguments**

<code>x</code>	<code>numeric()</code> vector.
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**Value**

A `numeric()` vector rounded to the nearest integer.

**Author(s)**

Nicholas J. Eagles

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<code>.construct_array</code>	<i>Construct a new Visium-like array encapsulating a set of spots</i>
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### Description

Given coords containing pixel coordinates of spots from potentially multiple capture areas, return a new Visium-like array encapsulating all such spots.

### Usage

```
.construct_array(coords, inter_spot_dist_px, buffer = 1)
```

### Arguments

<code>coords</code>	A <code>data.frame()</code> with columns <code>'pxl_row_in_fullres'</code> and <code>'pxl_col_in_fullres'</code> whose rows contain spots from potentially multiple capture areas.
<code>inter_spot_dist_px</code>	numeric(1) vector giving the pixel distance between any 2 spots in the new coordinates.
<code>buffer</code>	numeric(1) vector giving the number of spot distances to pad the new array (on all sides) beyond the min/max pixel coordinates in coords.

### Value

A [tibble](#) with columns `'array_row'`, `'array_col'`, `'pxl_row_in_fullres'`, and `'pxl_col_in_fullres'`, representing the new Visium-like array.

### Author(s)

Nicholas J. Eagles

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<code>.fit_to_array</code>	<i>Fit spots to a new Visium-like array: fast Euclidean approach</i>
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### Description

Given transformed pixel coordinates, modify the `'array_row'` and `'array_col'` columns to represent a larger Visium capture area containing all capture areas in a common coordinate system. The number of array rows/cols generally changes from the Visium standards of 78 and 128 (and even may change in ratio between num rows and num cols).

### Usage

```
.fit_to_array(coords, inter_spot_dist_px)
```

**Arguments**

`coords` A `data.frame()` whose rows represent capture areas of the same group, and containing columns `'array_row'`, `'array_col'`, `'pxl_row_in_fullres'`, and `'pxl_col_in_fullres'`.

`inter_spot_dist_px` `numeric(1)` vector giving the pixel distance between any 2 spots in the new coordinates.

**Details**

The mapping algorithm minimizes Euclidean distance of each source spot to each target spot. Runtime is  $O(n)$  with the number of spots, making it extremely fast. However, the Euclidean approach countintuitively may result in duplicated mappings (one source to the same target) as well as unexpected "holes" in the target array, which is often undesirable downstream.

**Value**

A [tibble](#) with modified `array_row` + `array_col` columns, as well as new `pxl_row_in_fullres_rounded` and `pxl_col_in_fullres_rounded` columns representing the pixel coordinates rounded to the nearest exact array coordinates.

**Author(s)**

Nicholas J. Eagles

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`.fit_to_array_lsap`      *Fit spots to a new Visium-like array: LSAP approach*

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**Description**

Given transformed pixel coordinates, modify the `'array_row'` and `'array_col'` columns to represent a larger Visium capture area containing all capture areas in a common coordinate system. The number of array rows/cols generally changes from the Visium standards of 78 and 128 (and even may change in ratio between num rows and num cols).

**Usage**

```
.fit_to_array_lsap(coords, inter_spot_dist_px)
```

**Arguments**

`coords` A `data.frame()` containing capture areas of the same group, and containing columns `'key'`, `'array_row'`, `'array_col'`, `'pxl_row_in_fullres'`, and `'pxl_col_in_fullres'`.

`inter_spot_dist_px` `numeric(1)` vector giving the pixel distance between any 2 spots in the new coordinates.

**Details**

Mapping to the proper array coordinates is framed as the linear sum assignment problem, and solved using the Hungarian algorithm. This approach is far slower than `.fit_to_array()`, running at  $O(n^3)$  with the number of spots, but guarantees a one-to-one mapping of starting to target spots, at a small cost in the Euclidean distance moved.

**Value**

A [tibble](#) with modified `array_row` + `array_col` columns, as well as new `pxl_row_in_fullres_rounded` and `pxl_col_in_fullres_rounded` columns representing the pixel coordinates rounded to the nearest exact array coordinates.

**Author(s)**

Nicholas J. Eagles

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<code>.get_neighbors</code>	<i>Get keys of neighboring spots</i>
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**Description**

For a given row of a `tibble()` containing array coordinates, find the associated spot's neighbors (belonging to the same capture area) and return their keys.

**Usage**

```
.get_neighbors(i, coords)
```

**Arguments**

<code>i</code>	An integer(1) giving a row index in <code>coords</code> .
<code>coords</code>	A <code>tibble()</code> containing <code>array_row</code> , <code>array_col</code> , <code>key</code> , and <code>capture_area</code> columns.

**Value**

A `character()` of neighboring spot keys.

**Author(s)**

Nicholas J. Eagles

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<code>.get_shared_neighbors</code>	<i>Calculate fraction of neighbors retained after mapping to new array coordinates</i>
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**Description**

Given `tibble()`s before and after mapping to new array coordinates, calculate for each spot the fraction of starting neighboring spots that were retained in the new array-coordinate system. Add this metric and return.

**Usage**

```
.get_shared_neighbors(coords_new, coords)
```

**Arguments**

- |                         |   |
|-------------------------|---|
| <code>coords_new</code> | A <code>tibble()</code> containing <code>array_row</code> , <code>array_col</code> , <code>key</code> , and <code>capture_area</code> columns, representing data after mapping to new array coordinates.  |
| <code>coords</code>     | A <code>tibble()</code> containing <code>array_row</code> , <code>array_col</code> , <code>key</code> , and <code>capture_area</code> columns, representing data before mapping to new array coordinates. |

**Value**

A `tibble()` copy of `coords_new` with additional `shared_neighbors` column.

**Author(s)**

Nicholas J. Eagles

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`.map_lsap`*Map source spots to best target spots by solving the LSAP*

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**Description**

Given `source_coords` and `target_coords`, both containing pixel coordinates of spots, map each spot in `source_coords` to a unique spot in `target_coords` such that the total squared Euclidean distance between matched spots is minimized, with guaranteed one-to-one mapping. This is done by solving the Linear Sum Assignment Problem (LSAP) using the Hungarian algorithm. Return the `source_coords` with the newly mapped `array_row` and `array_col` columns.

**Usage**

```
.map_lsap(source_coords, target_coords)
```

**Arguments**

- |                            |  |
|----------------------------|--|
| <code>source_coords</code> | A <code>data.frame()</code> containing the pixel coordinates (i.e. <code>'pxl_row_in_fullres'</code> and <code>'pxl_col_in_fullres'</code> ) of starting spots from one capture area.  |
| <code>target_coords</code> | A <code>data.frame()</code> containing the pixel coordinates (i.e. <code>'pxl_row_in_fullres'</code> and <code>'pxl_col_in_fullres'</code> ) of target spots which should just barely encompass the capture area in <code>source_coords</code> . |

**Value**

A [tibble](#) with the same rows as `source_coords`, but with the `array_row` and `array_col` columns (and rounded pixel coordinates) taken from the best-matching spots in `target_coords`.

**Author(s)**

Nicholas J. Eagles

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<code>.refine_fit</code>	<i>Return array coordinates fit to nearest spot with associated error</i>
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### Description

First, values of `x` are rounded to the nearest integer. Then, values of `y` are rounded to the nearest valid integer under the constraint that coordinates for `x` and `y` must be both odd or both even. These rounded values are returned, along with the Euclidean distance needed to move `x` and `y` from their original, non-integer values to their rounded values.

### Usage

```
.refine_fit(x, y, INTERVAL_X, INTERVAL_Y)
```

### Arguments

<code>x</code>	numeric() vector giving "ideal" array coordinates given every spot's transformed pixel coordinates.
<code>y</code>	Same as <code>x</code> , though <code>y</code> must represent ideal array columns iff <code>x</code> represents array rows, and vice versa.
<code>INTERVAL_X</code>	numeric(1) giving pixel distance between coordinate units used for <code>x</code> (e.g. if <code>x</code> represents ideal array_col values, <code>INTERVAL_X</code> represents pixel distance between spot columns).
<code>INTERVAL_Y</code>	numeric(1) giving pixel distance between coordinate units used for <code>y</code> .

### Value

A list consisting of 3 unnamed numeric() vectors: rounded `x`, rounded `y`, and the Euclidean distance in pixels from rounding both `x` and `y`.

### Author(s)

Nicholas J. Eagles

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<code>.validate_array</code>	<i>Check if coordinates are Visium-like</i>
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### Description

Sanity check designed to catch unforeseen bugs: halt if the tibble-like `coords`, expected to contain columns `'array_row'` and `'array_col'`, represents an invalid Visium array.

### Usage

```
.validate_array(coords)
```

### Arguments

<code>coords</code>	A data.frame() containing <code>'array_row'</code> and <code>'array_col'</code> columns calculated internally by <code>add_array_coords()</code> .
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**Value**

It returns NULL if all tests were correct.

**Author(s)**

Nicholas J. Eagles

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add_array_coords	<i>Add transformed array and pixel coordinates to a SpatialExperiment</i>
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**Description**

Given a [SpatialExperiment-class](#), sample information, and coordinates produced from the refinement workflow, add array and pixel coordinates appropriate for the linearly transformed capture areas making up each group present in the [SpatialExperiment-class](#).

**Usage**

```
add_array_coords(
  spe,
  sample_info,
  coords_dir,
  calc_error_metrics = FALSE,
  algorithm = c("LSAP", "Euclidean")
)
```

**Arguments**

spe	A <a href="#">SpatialExperiment-class</a> object.
sample_info	A <code>data.frame()</code> with columns <code>capture_area</code> , <code>group</code> , <code>fiji_xml_path</code> , <code>fiji_image_path</code> , <code>spaceranger_dir</code> , <code>intra_group_scalar</code> , and <code>group_hires_scalef</code> . The last two are made by <code>rescale_fiji_inputs()</code> .
coords_dir	A <code>character(1)</code> vector giving the directory containing sample directories each with <code>tissue_positions.csv</code> , <code>scalefactors_json.json</code> , and <code>tissue_lowres_image.png</code> files produced from refinement with <a href="#">prep_fiji_coords()</a> and related functions.
calc_error_metrics	A <code>logical(1)</code> vector indicating whether to calculate error metrics related to mapping spots to well-defined array coordinates. If <code>TRUE</code> , adds <code>euclidean_error</code> and <code>shared_neighbors</code> spot-level metrics to the <code>colData()</code> . The former indicates distance in number of inter-spot distances to "move" a spot to the new array position; the latter indicates the fraction of neighbors for the associated capture area that are retained after mapping, which can be quite time-consuming to compute.
algorithm	A <code>character(1)</code> vector indicating which mapping algorithm to employ when computing group-wide array coordinates. The default of "LSAP" is generally recommended, as it guarantees one-to-one mappings at the cost of computational time and some Euclidean error. The faster alternative "Euclidean" minimizes Euclidean error but may produce duplicate mappings, which is generally undesirable downstream (for clustering, etc).

## Details

Array coordinates are determined via an algorithm that fits each spot to the nearest spot on a new, imaginary, Visium-like capture area. The imaginary capture area differs from a real capture area only in its extent; array coordinates still start at 0 but may extend arbitrarily beyond the normal maximum indices of 77 and 127 to fit every capture area in each group defined in the [SpatialExperiment-class](#). The goal is to return well-defined array coordinates in a consistent spatial orientation for each group, such that downstream applications, such as clustering with BayesSpace, can process each group as if it really were one capture area in the first place. See <https://research.libd.org/visiumStitched/articles/visiumStitched.html#defining-array-coordinates> for more details.

## Value

A [SpatialExperiment-class](#) object with additional colData columns `pxl_row_in_fullres_[suffix]` and `pxl_col_in_fullres_[suffix]` with `[suffix]` values `original` and `rounded`; `array_row_original` and `array_col_original` columns; and modified `colData()` columns `array_row` and `array_col` and `spatialCoords()` with their transformed values.

## Author(s)

Nicholas J. Eagles

## Examples

```
if (!exists("spe")) {
  spe <- spatialLIBD::fetch_data(type = "visiumStitched_brain_spe")
}

#####
#   Prepare sample_info
#####

sample_info <- dplyr::tibble(
  group = "Br2719",
  capture_area = c("V13B23-283_A1", "V13B23-283_C1", "V13B23-283_D1")
)
#   Add 'spaceranger_dir' column
sr_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_spaceranger"),
  exdir = sr_dir
)
sample_info$spaceranger_dir <- file.path(
  sr_dir, sample_info$capture_area, "outs", "spatial"
)

#   Add Fiji-output-related columns
fiji_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_Fiji_out"),
  exdir = fiji_dir
)
sample_info$fiji_xml_path <- temp[grep("xml$", temp)]
sample_info$fiji_image_path <- temp[grep("png$", temp)]
```

```
## Re-size images and add more information to the sample_info
sample_info <- rescale_fiji_inputs(sample_info, out_dir = tempdir())

## Preparing Fiji coordinates and images for build_SpatialExperiment()
spe_input_dir <- tempdir()
prep_fiji_coords(sample_info, out_dir = spe_input_dir)
prep_fiji_image(sample_info, out_dir = spe_input_dir)

#####
#   Add array coordinates
#####

#   Run with Euclidean algorithm for speed. On real analyses, "LSAP" is
#   generally recommended.
spe_new <- add_array_coords(
  spe, sample_info, tempdir(), algorithm = "Euclidean"
)

#   Several columns related to spatial coordinates were added
added_cols_regex <- "^(array|pxl)_(row|col)(_in_fullres)?_(original|rounded)$"
colnames(SummarizedExperiment::colData(spe_new))[
  grep(added_cols_regex, colnames(SummarizedExperiment::colData(spe_new)))
]

#   'array_row', 'array_col', and spatialCoords() were overwritten with
#   their transformed values
head(spe$array_row)
head(spe$array_col)
head(SpatialExperiment::spatialCoords(spe_new))
```

---

add\_overlap\_info

---

*Add info about how spots overlap among capture areas*


---

## Description

Given a [SpatialExperiment-class](#) and column name in its colData, return a modified copy of the SpatialExperiment with additional colData columns: spe\$exclude\_overlapping and spe\$overlap\_key.

## Usage

```
add_overlap_info(spe, metric_name)
```

## Arguments

spe	A <a href="#">SpatialExperiment-class</a> with colData(spe) columns array_row, array_col, key, and capture_area.
metric_name	character(1) in colnames(colData(spe)), where spots belonging to the capture area with highest average value for the metric take precedence over other spots.

## Details

spe\$exclude\_overlapping is TRUE for spots with a higher-quality overlapping capture area and FALSE otherwise. [vis\\_clus](#) only displays FALSE spots to prevent overplotting in regions of overlap. spe\$overlap\_key gives comma-separated strings containing the keys of any overlapping spots, and is the empty string otherwise.

## Value

A [SpatialExperiment](#) object with additional colData columns spe\$exclude\_overlapping and spe\$overlap\_key.

## Author(s)

Nicholas J. Eagles

## Examples

```
if (!exists("spe")) {
  spe <- spatialLIBD::fetch_data(type = "visiumStitched_brain_spe")
}

# Find the mean of the 'sum_umi' metric by capture area to understand
# which capture areas will be excluded in regions of overlap
SummarizedExperiment::colData(spe) |>
  dplyr::as_tibble() |>
  dplyr::group_by(capture_area) |>
  dplyr::summarize(mean_sum_umi = mean(sum_umi))

spe <- add_overlap_info(spe, "sum_umi")

# See how many spots were excluded by capture area
table(spe$exclude_overlapping, spe$capture_area)

# Examine how data about overlapping spots is stored (for the first
# few spots with overlap)
head(spe$overlap_key[spe$overlap_key != ""])
```

---

as.Seurat

---

*Convert a SpatialExperiment object to a Seurat object*


---

## Description

Given a [SpatialExperiment-class](#) object, first `as.Seurat()` is run, which operates on [SingleCellExperiment-class](#) objects. The remaining components (images, spatial coordinates) are added manually. The actual appearance of images are buggy for now.

## Usage

```
as.Seurat(
  spe,
  spatial_cols = c(tissue = "in_tissue", row = "array_row", col = "array_col", imagerow =
    "pxl_row_in_fullres", imagecol = "pxl_col_in_fullres"),
  verbose = TRUE
)
```

**Arguments**

spe	A <a href="#">SpatialExperiment-class</a> with colData() or spatialCoords() columns given by spatial_cols. This does not have to be a stitched spe object as this function should work with any type of spe objects.
spatial_cols	A character(5) named vector mapping which colData(spe) or spatialCoords(spe) columns contain the tissue, row, col, imagerow, and imagecol information expected by Seurat.
verbose	A logical(1) vector. If TRUE, print status update about the conversion process. This information can be useful for debugging.

**Details**

Note that only the lowres images from imgData(spe) will be used.

**Value**

A Seurat object.

**Author(s)**

Nicholas J. Eagles

**Examples**

```
## Download some example data
spe_unstitched <- spatialLIBD::fetch_data(
  type = "spatialDLPFC_Visium_example_subset"
)[seq(100), seq(100)]

## Make the column names unique
colnames(spe_unstitched) <- spatialLIBD::add_key(spe_unstitched)$key

## Convert from a SpatialExperiment to a Seurat object
seur <- as.Seurat(spe_unstitched)
seur

## Example with an stitched SPE object
if (!exists("spe")) {
  spe <- spatialLIBD::fetch_data(type = "visiumStitched_brain_spe")
}
seur_stitched <- as.Seurat(spe[seq(100), seq(100)])

## Let's look at our resulting Seurat object
seur_stitched
```

---

build\_SpatialExperiment

*Build stitched SpatialExperiment*

---

## Description

First, read in capture-area-level SpaceRanger <https://www.10xgenomics.com/support/software/space-ranger/latest/analysis/running-pipelines/space-ranger-count> outputs. Then, overwrite spatial coordinates and images to represent group-level samples using `sample_info$group` (though keep original coordinates in `colData` columns ending with the suffix `"_original"`). Next, add info about overlaps (via `spe$exclude_overlapping` and `spe$overlap_key`). Ultimately, return a `SpatialExperiment-class` ready for visualization or downstream analysis.

## Usage

```
build_SpatialExperiment(
  sample_info,
  coords_dir,
  count_type = c("sparse", "HDF5"),
  data_type = c("raw", "filtered"),
  reference_gtf = NULL,
  gtf_cols = c("source", "type", "gene_id", "gene_version", "gene_name", "gene_type"),
  calc_error_metrics = FALSE,
  algorithm = c("LSAP", "Euclidean")
)
```

## Arguments

<code>sample_info</code>	A <code>data.frame()</code> with columns <code>capture_area</code> , <code>group</code> , <code>fiji_xml_path</code> , <code>fiji_image_path</code> , <code>spaceranger_dir</code> , <code>intra_group_scalar</code> , and <code>group_hires_scalef</code> . The last two are made by <code>rescale_fiji_inputs()</code> .
<code>coords_dir</code>	A <code>character(1)</code> vector giving the directory containing sample directories each with <code>tissue_positions.csv</code> , <code>scalefactors.json.json</code> , and <code>tissue_lowres_image.png</code> files produced from refinement with <code>prep_fiji_coords()</code> and related functions.
<code>count_type</code>	A <code>character(1)</code> vector passed to <code>type</code> from <code>SpatialExperiment::read10xVisiumWrapper</code> , defaulting to <code>"sparse"</code> .
<code>data_type</code>	A <code>character(1)</code> vector passed to <code>data</code> from <code>SpatialExperiment::read10xVisiumWrapper</code> , defaulting to <code>"raw"</code> .
<code>reference_gtf</code>	Passed to <code>spatialLIBD::read10xVisiumWrapper()</code> . If working on the same system where SpaceRanger was run, the GTF will be automatically found; otherwise a <code>character(1)</code> path may be supplied, pointing to a GTF file of gene annotation to populate <code>rowData()</code> with.
<code>gtf_cols</code>	Passed to <code>spatialLIBD::read10xVisiumWrapper()</code> . Columns in the reference GTF to extract and populate <code>rowData()</code> .
<code>calc_error_metrics</code>	A <code>logical(1)</code> vector indicating whether to calculate error metrics related to mapping spots to well-defined array coordinates. If <code>TRUE</code> , adds <code>euclidean_error</code> and <code>shared_neighbors</code> spot-level metrics to the <code>colData()</code> . The former indicates distance in number of inter-spot distances to "move" a spot to the new array position; the latter indicates the fraction of neighbors for the associated capture area that are retained after mapping, which can be quite time-consuming to compute.
<code>algorithm</code>	A <code>character(1)</code> vector indicating which mapping algorithm to employ when computing group-wide array coordinates. The default of <code>"LSAP"</code> is generally

recommended, as it guarantees one-to-one mappings at the cost of computational time and some Euclidean error. The faster alternative "Euclidean" minimizes Euclidean error but may produce duplicate mappings, which is generally undesirable downstream (for clustering, etc).

## Value

A [SpatialExperiment-class](#) object with one sample per group specified in `sample_info` using transformed pixel and array coordinates (including in the `spatialCoords()`).

## Author(s)

Nicholas J. Eagles

## Examples

```
#####
#   Prepare sample_info
#####

sample_info <- dplyr::tibble(
  group = "Br2719",
  capture_area = c("V13B23-283_A1", "V13B23-283_C1", "V13B23-283_D1")
)
#   Add 'spaceranger_dir' column
sr_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_spaceranger"),
  exdir = sr_dir
)
sample_info$spaceranger_dir <- file.path(
  sr_dir, sample_info$capture_area, "outs", "spatial"
)

#   Add Fiji-output-related columns
fiji_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_Fiji_out"),
  exdir = fiji_dir
)
sample_info$fiji_xml_path <- temp[grep("xml$", temp)]
sample_info$fiji_image_path <- temp[grep("png$", temp)]

## Re-size images and add more information to the sample_info
sample_info <- rescale_fiji_inputs(sample_info, out_dir = tempdir())

## Preparing Fiji coordinates and images for build_SpatialExperiment()
spe_input_dir <- tempdir()
prep_fiji_coords(sample_info, out_dir = spe_input_dir)
prep_fiji_image(sample_info, out_dir = spe_input_dir)

#####
#   Build the SpatialExperiment
#####

#   Since we don't have access to the original GTF used to run SpaceRanger,
#   we must explicitly supply our own GTF to build_SpatialExperiment(). We use
```

```
# GENCODE release 32, intended to be quite close to the actual GTF used,
# which is available from:
# https://cf.10xgenomics.com/supp/cell-exp/refdata-gex-GRCh38-2024-A.tar.gz
bfc <- BiocFileCache::BiocFileCache()
gtf_cache <- BiocFileCache::bfcpath(
  bfc,
  paste0(
    "ftp://ftp.ebi.ac.uk/pub/databases/genocode/Gencode_human/",
    "release_32/genocode.v32.annotation.gtf.gz"
  )
)

## Now we can build the stitched SpatialExperiment object. Use the Euclidean
## algorithm for calculating new array coordinates because of speed in this
## example, but "LSAP" is generally recommended.
spe <- build_SpatialExperiment(
  sample_info, coords_dir = spe_input_dir, reference_gtf = gtf_cache,
  algorithm = "Euclidean"
)

## Let's explore the stitched SpatialExperiment object
spe
```

---

merge_overlapping	<i>Merge overlapping spots</i>
-------------------	--------------------------------

---

## Description

Given a stitched [SpatialExperiment-class](#), merge overlapping (same array coordinates) spots by adding expression (i.e. from `assays(spe)$counts`), returning a `SpatialExperiment` with at most one spot per array location.

## Usage

```
merge_overlapping(spe)
```

## Arguments

spe	A <a href="#">SpatialExperiment-class</a> with <code>colData(spe)</code> columns <code>array_row</code> , <code>array_col</code> , <code>key</code> , <code>group</code> , and <code>capture_area</code> .
-----	--

## Details

`colData(spe)` and `spatialCoords(spe)` of the merged spots are taken from the spots whose `exclude_overlapping` values are `TRUE`.

## Value

A [SpatialExperiment](#) with at most one spot per array location

## Author(s)

Nicholas J. Eagles



## Examples

```
if (!exists("spe")) {
  spe <- spatialLIBD::fetch_data(type = "visiumStitched_brain_spe")
}

# Group colData by group and array coordinates
grouped_coldata <- colData(spe) |>
  dplyr::as_tibble() |>
  dplyr::group_by(group, array_row, array_col)

# Find the first 100 keys that overlap other spots and don't, respectively
overlapping_keys <- grouped_coldata |>
  dplyr::filter(dplyr::n() > 1) |>
  dplyr::slice_head(n = 2) |>
  dplyr::ungroup() |>
  dplyr::slice_head(n = 100) |>
  dplyr::pull(key)
nonoverlapping_keys <- grouped_coldata |>
  dplyr::filter(dplyr::n() == 1) |>
  dplyr::ungroup() |>
  dplyr::slice_head(n = 100) |>
  dplyr::pull(key)

# Built a small SPE containing some overlaps and some non-overlapping spots
small_spe <- spe[, c(overlapping_keys, nonoverlapping_keys)]

# Merge overlapping spots
small_spe_merged <- merge_overlapping(small_spe)

# All array coordinates have just one unique spot after merging
colData(small_spe_merged) |>
  dplyr::as_tibble() |>
  dplyr::group_by(group, array_row, array_col) |>
  dplyr::summarize(n = dplyr::n()) |>
  dplyr::pull(n) |>
  table()
```

---

```
prep_fiji
```

---

*Prepare Fiji outputs for building a SpatialExperiment*

---

## Description

Together, `prep_fiji_image()` and `prep_fiji_coords()` process Fiji outputs and generate one directory per group resembling Spaceranger's **spatial outputs**; in particular, `tissue_positions.csv`, `tissue_lowres_image.png`, and `scalefactors.json`. `json` files are created. These functions are necessary to run in preparation for `build_SpatialExperiment()`.

## Usage

```
prep_fiji_image(sample_info, out_dir, lowres_max_size = 1200)

prep_fiji_coords(sample_info, out_dir)
```

## Arguments

sample_info	A data.frame() with columns capture_area, group, fiji_xml_path, fiji_image_path, spaceranger_dir, intra_group_scalar, and group_hires_scalef. The last two are made by rescale_fiji_inputs().
out_dir	A character(1) vector giving a path to a directory to place the output pixel coordinates CSVs. It must exist in advance.
lowres_max_size	An integer(1) vector: the resolution (number of pixels) of the larger dimension of the output image(s), considered to be "low resolution". The default value of 1200 assumes that you are stitching together at most a 2 by 2 grid of Visium capture areas, where each has at most 600 pixels on the longest dimension (as is the default in SpaceRanger).

## Details

Given a data.frame() of sample information (sample\_info) with columns capture\_area, group, and fiji\_xml\_path, expected to have one unique path to Fiji XML output per group, prep\_fiji\_coords reads in the pixel coordinates from each capture area's tissue\_positions.csv file from SpaceRanger, and transform using the rotation matrix specified by Fiji <https://imagej.net/software/fiji/>. It writes one new tissue\_positions.csv file per group.

After stitching all groups in sample\_info with Fiji, images of various resolutions (pixel dimensions) are left. prep\_fiji\_image() creates copies of each image whose largest dimension is lowres\_max\_size pixels. It also creates a corresponding scalefactors\_json.json file much like SpaceRanger's.

## Value

This function returns a character() with the file paths to the files it created. For prep\_fiji\_coords(), these are the tissue\_positions.csv files; for prep\_fiji\_image(), these are the tissue\_lowres\_image.png and scalefactors\_json.json files.

## Functions

- prep\_fiji\_image(): Create low-res images and scale factors from high-res Fiji output images
- prep\_fiji\_coords(): Apply transform info from Fiji XML output

## Author(s)

Nicholas J. Eagles

## Examples

```
sample_info <- dplyr::tibble(
  group = "Br2719",
  capture_area = c("V13B23-283_A1", "V13B23-283_C1", "V13B23-283_D1")
)
# Add 'spaceranger_dir' column
sr_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_spaceranger"),
  exdir = sr_dir
)
```

```

sample_info$spaceranger_dir <- file.path(
  sr_dir, sample_info$capture_area, "outs", "spatial"
)

# Add Fiji-output-related columns
fiji_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_Fiji_out"),
  exdir = fiji_dir
)
sample_info$fiji_xml_path <- temp[grep("xml$", temp)]
sample_info$fiji_image_path <- temp[grep("png$", temp)]

## Re-size images and add more information to the sample_info
sample_info <- rescale_fiji_inputs(sample_info, out_dir = tempdir())

spe_input_dir <- tempdir()
out_paths_image <- prep_fiji_image(
  sample_info,
  out_dir = spe_input_dir, lowres_max_size = 1000
)
out_path_coords <- prep_fiji_coords(sample_info, out_dir = spe_input_dir)

# A "low resolution" stitched image was produced, which has 1000
# pixels in its largest dimension
this_image <- imager::load.image(
  file.path(spe_input_dir, "Br2719", "tissue_lowres_image.png")
)
dim(this_image)
library("imager")
plot(this_image)

# 'prep_fiji_image' produced an image and scalefactors
out_paths_image

# 'prep_fiji_coords' produced a file of spatial coordinates for the
# stitched Br2719
readr::read_csv(out_path_coords)

```

---

rescale\_fiji\_inputs      *Write same-scale hires images for input to Fiji*

---

## Description

Given a `data.frame()` of sample information (`sample_info`) with columns `capture_area`, `group`, and `spaceranger_dir`, Write new high-resolution images for use as input to Fiji <https://imagej.net/software/fiji/>. Particularly when capture areas come from different slides, there is a risk of significant scale differences among SpaceRanger's `tissue_hires_image.png` images; that is, the physical distance represented by a pixel from each capture area may differ nontrivially, leading to a distance-distorted output image, and inconsistent scaling when later transforming pixel coordinates. This function writes approximately high-res images whose pixels are of equal physical size within each group, then adds `intra_group_scalar` and `group_hires_scalef` columns to `sample_info`. `intra_group_scalar` gives the scalar by which a given capture area's `tissue_hires_image.png` image and pixel coordinates must be multiplied to match the scale of other group members; `group_hires_scalef`

gives the new `tissue_hires_scalef` (as from SpaceRanger's `scalefactors_json.json` file) appropriate for every capture area from the group.

### Usage

```
rescale_fiji_inputs(sample_info, out_dir)
```

### Arguments

<code>sample_info</code>	A <code>data.frame()</code> with columns <code>capture_area</code> , <code>group</code> , <code>fiji_xml_path</code> , <code>fiji_image_path</code> , <code>spaceranger_dir</code> , <code>intra_group_scalar</code> , and <code>group_hires_scalef</code> . The last two are made by <code>rescale_fiji_inputs()</code> .
<code>out_dir</code>	A <code>character(1)</code> vector giving a path to a directory to place the output images, which must exist in advance.

### Value

A [tibble](#): a copy of `sample_info` with additional columns `intra_group_scalar` and `group_hires_scalef`.

### Author(s)

Nicholas J. Eagles

### Examples

```
# Define sample information for the example human brain data
sample_info <- dplyr::tibble(
  group = "Br2719",
  capture_area = c("V13B23-283_A1", "V13B23-283_C1", "V13B23-283_D1")
)
# Add 'spaceranger_dir' column
sr_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_spaceranger"),
  exdir = sr_dir
)
sample_info$spaceranger_dir <- file.path(
  sr_dir, sample_info$capture_area, "outs", "spatial"
)

# Add Fiji-output-related columns
fiji_dir <- tempdir()
temp <- unzip(
  spatialLIBD::fetch_data("visiumStitched_brain_Fiji_out"),
  exdir = fiji_dir
)
sample_info$fiji_xml_path <- temp[grepl("xml$", temp)]
sample_info$fiji_image_path <- temp[grepl("png$", temp)]

## Re-size images and add more information to the sample_info
out_dir <- tempdir()
sample_info_new <- rescale_fiji_inputs(sample_info, out_dir = out_dir)

# Scale factors are computed that are necessary downstream (i.e. with
# prep_fiji_*() functions)
sample_info_new[, setdiff(colnames(sample_info_new), colnames(sample_info))]
```

```
# Image are produced that are ready for alignment in Fiji  
list.files(out_dir)
```

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