

# Package ‘autoBagging’

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**Type** Package

**Title** Learning to Rank Bagging Workflows with Metalearning

**Version** 0.1.0

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**Description** A framework for automated machine learning. Concretely, the focus is on the optimisation of bagging workflows. A bagging workflows is composed by three phases: (i) generation: which and how many predictive models to learn; (ii) pruning: after learning a set of models, the worst ones are cut off from the ensemble; and (iii) integration: how the models are combined for predicting a new observation. autoBagging optimises these processes by combining metalearning and a learning to rank approach to learn from metadata. It automatically ranks 63 bagging workflows by exploiting past performance and dataset characterization. A complete description of the method can be found in: Pinto, F., Cerqueira, V., Soares, C., Mendes-Moreira, J. (2017): ``autoBagging: Learning to Rank Bagging Workflows with Metalearning'' arXiv preprint arXiv:1706.09367.

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---

abmodel

*abmodel*

---

## Description

abmodel

## Usage

```
abmodel(base_models, form, data, dynamic_selection)
```

## Arguments

|                   |   |
|-------------------|---|
| base_models       | a list of decision tree classifiers   |
| form              | formula   |
| data              | dataset used to train base_models   |
| dynamic_selection | the dynamic selection/combination method to use to aggregate predictions. If none, majority vote is used. |

---

abmodel-class

*abmodel-class*

---

## Description

**abmodel** is an S4 class that contains the ensemble model. Besides the base learning algorithms—`base_models` – **abmodel** class contains information about the dynamic selection method to apply in new data.

## Slots

|                   |  |
|-------------------|--|
| base_models       | a list of decision tree classifiers  |
| form              | formula  |
| data              | dataset used to train base_models  |
| dynamic_selection | the dynamic selection/combination method to use to aggregate predictions.<br>If none, majority vote is used. |

## See Also

[autoBagging](#) function for the method of automatic predicting of the best workflows.

---

`autoBagging`*autoBagging*

---

## Description

### Learning to Rank Bagging Workflows with Metalearning

Machine Learning (ML) has been successfully applied to a wide range of domains and applications. One of the techniques behind most of these successful applications is Ensemble Learning (EL), the field of ML that gave birth to methods such as Random Forests or Boosting. The complexity of applying these techniques together with the market scarcity on ML experts, has created the need for systems that enable a fast and easy drop-in replacement for ML libraries. Automated machine learning (autoML) is the field of ML that attempts to answers these needs. Typically, these systems rely on optimization techniques such as bayesian optimization to lead the search for the best model. Our approach differs from these systems by making use of the most recent advances on metalearning and a learning to rank approach to learn from metadata. We propose autoBagging, an autoML system that automatically ranks 63 bagging workflows by exploiting past performance and dataset characterization. Results on 140 classification datasets from the OpenML platform show that autoBagging can yield better performance than the Average Rank method and achieve results that are not statistically different from an ideal model that systematically selects the best workflow for each dataset.

## Usage

```
autoBagging(form, data)
```

## Arguments

|                   |  |
|-------------------|--|
| <code>form</code> | formula. Currently supporting only categorical target variables (classification tasks) |
| <code>data</code> | training dataset with a categorical target variable                                    |

## Details

The underlying model leverages the performance of the workflows in historical data. It ranks and recommends workflows for a given classification task. A bagging workflow is comprised by the following steps:

**generation** the number of trees to grow

**pruning** the pruning of low performing trees in the ensemble

**pruning cut-point** a parameter of the previous step

**dynamic selection** the dynamic selection method used to aggregate predictions. If none is recommended, majority voting is used.

## Value

an abmodel class object

## References

Pinto, F., Cerqueira, V., Soares, C., Mendes-Moreira, J.: "autoBagging: Learning to Rank Bagging Workflows with Metalearning" arXiv preprint arXiv:1706.09367 (2017).

## See Also

[bagging](#) for the bagging pipeline with a specific workflow; [baggedtrees](#) for the bagging implementation; [abmodel-class](#) for the returning class object.

## Examples

```
## Not run:
# splitting an example dataset into train/test:
train <- iris[1:(.7*nrow(iris)), ]
test <- iris[-c(1:(.7*nrow(iris))), ]
# then apply autoBagging to the train, using the desired formula:
# autoBagging will compute metafeatures on the dataset
# and apply a pre-trained ranking model to recommend a workflow.
model <- autoBagging(Species ~., train)
# predictions are produced with the standard predict method
preds <- predict(model, test)

## End(Not run)
```

baggedtrees

*bagged trees models*

## Description

The standard resampling with replacement (bootstrap) is used as sampling strategy.

## Usage

```
baggedtrees(form, data, ntree = 100)
```

## Arguments

|       |               |
|-------|---------------|
| form  | formula       |
| data  | training data |
| ntree | no of trees   |

## Examples

```
ensemble <- baggedtrees(Species ~., iris, ntree = 50)
```

|         |                       |
|---------|-----------------------|
| bagging | <i>bagging method</i> |
|---------|-----------------------|

## Description

bagging method

## Usage

```
bagging(form, data, ntrees, pruning, dselection, pruning_cp)
```

## Arguments

|            |   |
|------------|---|
| form       | formula   |
| data       | training data   |
| ntrees     | ntrees  |
| pruning    | model pruning method. A character vector. Currently, the following methods are supported:<br><b>mdsq</b> Margin-distance minimisation<br><b>bb</b> boosting based pruning<br><b>none</b> no pruning   |
| dselection | dynamic selection of the available models. Currently, the following methods are supported:<br><b>ola</b> Overall Local Accuracy<br><b>knora-e</b> K-nearest-oracles-eliminate<br><b>none</b> no dynamic selection. Majority voting is used. |
| pruning_cp | The pruning cutpoint for the pruning method picked.   |

## See Also

[baggedtrees](#) for the implementation of the bagging model.

## Examples

```
# splitting an example dataset into train/test:
train <- iris[1:(.7*nrow(iris)), ]
test <- iris[-c(1:(.7*nrow(iris))), ]
form <- Species ~.
# a user-defined bagging workflow
m <- bagging(form, iris, ntrees = 5, pruning = "bb", pruning_cp = .5, dselection = "ola")
preds <- predict(m, test)
# a standard bagging workflow with 5 trees (5 trees for exemplification purposes):
m2 <- bagging(form, iris, ntrees = 5, pruning = "none", dselection = "none")
preds2 <- predict(m2, test)
```

---

**bb***Boosting-based pruning of models*

---

**Description**

Boosting-based pruning of models

**Usage**

```
bb(form, preds, data, cutPoint)
```

**Arguments**

|          |  |
|----------|--|
| form     | formula  |
| preds    | predictions in training data                   |
| data     | training data                                  |
| cutPoint | ratio of the total number of models to cut off |

---

**classmajority.landmarker***classmajority.landmarker*

---

**Description**

classmajority.landmarker

**Usage**

```
classmajority.landmarker(dataset, data.char)
```

**Arguments**

|           |                               |
|-----------|-------------------------------|
| dataset   | train data for the landmarker |
| data.char | dc                            |

---

```
classmajority.landmarker.correlation  
      classmajority.landmarker.correlation
```

---

**Description**

`classmajority.landmarker.correlation`

**Usage**

```
classmajority.landmarker.correlation(dataset, data.char)
```

**Arguments**

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

```
classmajority.landmarker.entropy  
      classmajority.landmarker.entropy
```

---

**Description**

`classmajority.landmarker.entropy`

**Usage**

```
classmajority.landmarker.entropy(dataset, data.char)
```

**Arguments**

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

**classmajority.landmarker.interinfo**  
*classmajority.landmarker.interinfo*

---

### Description

`classmajority.landmarker.interinfo`

### Usage

`classmajority.landmarker.interinfo(dataset, data.char)`

### Arguments

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

**classmajority.landmarker.mutual.information**  
*classmajority.landmarker.mutual.information*

---

### Description

`classmajority.landmarker.mutual.information`

### Usage

`classmajority.landmarker.mutual.information(dataset, data.char)`

### Arguments

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

**ContAttrs**

*Retrieve names of continuous attributes (not including the target)*

---

**Description**

Retrieve names of continuous attributes (not including the target)

**Usage**

```
ContAttrs(dataset)
```

**Arguments**

dataset        structure describing the data set, according to `read_data.R`

**Value**

list of strings

**See Also**

`read_data.R`

---

**dstump.landmarker\_d1     *dstump.landmarker\_d1***

---

**Description**

`dstump.landmarker_d1`

**Usage**

```
dstump.landmarker_d1(dataset, data.char)
```

**Arguments**

dataset        train data for the landmarker

data.char      dc

---

dstump.landmarker\_d1.correlation  
*dstump.landmarker\_d1.correlation*

---

**Description**

*dstump.landmarker\_d1.correlation*

**Usage**

`dstump.landmarker_d1.correlation(dataset, data.char)`

**Arguments**

|           |                             |
|-----------|-----------------------------|
| dataset   | train data for the landmark |
| data.char | dc                          |

---

---

dstump.landmarker\_d1.entropy  
*dstump.landmarker\_d1.entropy*

---

**Description**

*dstump.landmarker\_d1.entropy*

**Usage**

`dstump.landmarker_d1.entropy(dataset, data.char)`

**Arguments**

|           |                             |
|-----------|-----------------------------|
| dataset   | train data for the landmark |
| data.char | dc                          |

---

```
dstump.landmarker_d1.interinfo  
      dstump.landmarker_d1.interinfo
```

---

**Description**

`dstump.landmarker_d1.interinfo`

**Usage**

```
dstump.landmarker_d1.interinfo(dataset, data.char)
```

**Arguments**

|                        |                             |
|------------------------|-----------------------------|
| <code>dataset</code>   | train data for the landmark |
| <code>data.char</code> | dc                          |

---

```
dstump.landmarker_d1.mutual.information  
      dstump.landmarker_d1.mutual.information
```

---

**Description**

`dstump.landmarker_d1.mutual.information`

**Usage**

```
dstump.landmarker_d1.mutual.information(dataset, data.char)
```

**Arguments**

|                        |                             |
|------------------------|-----------------------------|
| <code>dataset</code>   | train data for the landmark |
| <code>data.char</code> | dc                          |

---

dstump.landmarker\_d2    *dstump.landmarker\_d2*

---

**Description**

`dstump.landmarker_d2`

**Usage**

`dstump.landmarker_d2(dataset, data.char)`

**Arguments**

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

---

dstump.landmarker\_d2.correlation  
                      *dstump.landmarker\_d2.correlation*

---

**Description**

`dstump.landmarker_d2.correlation`

**Usage**

`dstump.landmarker_d2.correlation(dataset, data.char)`

**Arguments**

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

dstump.landmarker\_d2.entropy  
*dstump.landmarker\_d2.entropy*

---

**Description**

dstump.landmarker\_d2.entropy

**Usage**

dstump.landmarker\_d2.entropy(dataset, data.char)

**Arguments**

|           |                             |
|-----------|-----------------------------|
| dataset   | train data for the landmark |
| data.char | dc                          |

---

dstump.landmarker\_d2.interinfo  
*dstump.landmarker\_d2.interinfo*

---

**Description**

dstump.landmarker\_d2.interinfo

**Usage**

dstump.landmarker\_d2.interinfo(dataset, data.char)

**Arguments**

|           |                             |
|-----------|-----------------------------|
| dataset   | train data for the landmark |
| data.char | dc                          |

---

```
dstump.landmarker_d2.mutual.information  
      dstump.landmarker_d2.mutual.information
```

---

**Description**

*dstump.landmarker\_d2.mutual.information*

**Usage**

```
dstump.landmarker_d2.mutual.information(dataset, data.char)
```

**Arguments**

|           |                               |
|-----------|-------------------------------|
| dataset   | train data for the landmarker |
| data.char | dc                            |

---

---

```
dstump.landmarker_d3    dstump.landmarker_d3
```

---

**Description**

*dstump.landmarker\_d3*

**Usage**

```
dstump.landmarker_d3(dataset, data.char)
```

**Arguments**

|           |                               |
|-----------|-------------------------------|
| dataset   | train data for the landmarker |
| data.char | dc                            |

---

```
dstump.landmarker_d3.correlation  
      dstump.landmarker_d3.correlation
```

---

**Description**

`dstump.landmarker_d3.correlation`

**Usage**

```
dstump.landmarker_d3.correlation(dataset, data.char)
```

**Arguments**

|                        |                             |
|------------------------|-----------------------------|
| <code>dataset</code>   | train data for the landmark |
| <code>data.char</code> | dc                          |

---

```
dstump.landmarker_d3.entropy  
      dstump.landmarker_d3.entropy
```

---

**Description**

`dstump.landmarker_d3.entropy`

**Usage**

```
dstump.landmarker_d3.entropy(dataset, data.char)
```

**Arguments**

|                        |                             |
|------------------------|-----------------------------|
| <code>dataset</code>   | train data for the landmark |
| <code>data.char</code> | dc                          |

---

**dstump.landmarker\_d3.interinfo**  
*dstump.landmarker\_d3.interinfo*

---

**Description**

*dstump.landmarker\_d3.interinfo*

**Usage**

`dstump.landmarker_d3.interinfo(dataset, data.char)`

**Arguments**

|                        |                             |
|------------------------|-----------------------------|
| <code>dataset</code>   | train data for the landmark |
| <code>data.char</code> | dc                          |

---

**dstump.landmarker\_d3.mutual.information**  
*dstump.landmarker\_d3.mutual.information*

---

**Description**

*dstump.landmarker\_d3.mutual.information*

**Usage**

`dstump.landmarker_d3.mutual.information(dataset, data.char)`

**Arguments**

|                        |                             |
|------------------------|-----------------------------|
| <code>dataset</code>   | train data for the landmark |
| <code>data.char</code> | dc                          |

**GetMeasure***Retrieve the value of a previously computed measure***Description**

Retrieve the value of a previously computed measure

**Usage**

```
GetMeasure(inDCName, inDCSet, component.name = "value")
```

**Arguments**

`inDCName`

name of data characteristics

`inDCSet`

set of data characteristics already computed

`component.name`

name of component (e.g. time or value) to retrieve; if NULL retrieve all

**Value**

simple or structured value

**Note**

if measure is not available, stop execution with error

**get\_target***get target variable***Description**

get the target variable from a formula

**Usage**

```
get_target(form)
```

**Arguments**

`form`

formula

---

KNORA.E*K-Nearest-ORACLE-Eliminate*

---

**Description**

A dynamic selection method

**Usage**

```
KNORA.E(form, mod, v.data, t.data, k = 5)
```

**Arguments**

|        |   |
|--------|---|
| form   | formula   |
| mod    | a list comprising the individual models         |
| v.data | validation data                                 |
| t.data | test data, with the instances to predict        |
| k      | the number of nearest neighbors. Defaults to 5. |

---

```
lda.landmarker.correlation
```

---

*lda.landmarker.correlation*

---

**Description**

```
lda.landmarker.correlation
```

**Usage**

```
## S3 method for class 'landmarker.correlation'
lda(dataset, data.char)
```

**Arguments**

|           |                             |
|-----------|-----------------------------|
| dataset   | train data for the landmark |
| data.char | dc                          |

---

**majority\_voting**      *majority voting*

---

**Description**

majority voting

**Usage**

`majority_voting(x)`

**Arguments**

`x`      predictions produced by a set of models

---

**mdsq**      *Margin Distance Minimization*

---

**Description**

Margin Distance Minimization

**Usage**

`mdsq(form, preds, data, cutPoint)`

**Arguments**

`form`      formula

`preds`      predictions in training data

`data`      training data

`cutPoint`      ratio of the total number of models to cut off

---

`nb.landmarker`*nb.landmarker*

---

**Description**`nb.landmarker`**Usage**`nb.landmarker(dataset, data.char)`**Arguments**

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

`nb.landmarker.correlation`*nb.landmarker.correlation*

---

**Description**`nb.landmarker.correlation`**Usage**`nb.landmarker.correlation(dataset, data.char)`**Arguments**

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

**nb.landmarker.entropy** *nb.landmarker.entropy*

---

### Description

`nb.landmarker.entropy`

### Usage

`nb.landmarker.entropy(dataset, data.char)`

### Arguments

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

**nb.landmarker.interinfo** *nb.landmarker.interinfo*

---

### Description

`nb.landmarker.interinfo`

### Usage

`nb.landmarker.interinfo(dataset, data.char)`

### Arguments

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

```
nb.landmarker.mutual.information  
      nb.landmarker.mutual.information
```

---

**Description**

`nb.landmarker.mutual.information`

**Usage**

```
nb.landmarker.mutual.information(dataset, data.char)
```

**Arguments**

|                        |                               |
|------------------------|-------------------------------|
| <code>dataset</code>   | train data for the landmarker |
| <code>data.char</code> | dc                            |

---

|     |                               |
|-----|-------------------------------|
| OLA | <i>Overall Local Accuracy</i> |
|-----|-------------------------------|

---

**Description**

A dynamic selection method

**Usage**

```
OLA(form, mod, v.data, t.data, k = 5)
```

**Arguments**

|                     |   |
|---------------------|---|
| <code>form</code>   | formula   |
| <code>mod</code>    | a list comprising the individual models         |
| <code>v.data</code> | validation data                                 |
| <code>t.data</code> | test data, with the instances to predict        |
| <code>k</code>      | the number of nearest neighbors. Defaults to 5. |

---

`predict,abmodel-method`

*Predicting on new data with a **abmodel** model*

---

### Description

This is a predict method for predicting new data points using a abmodel class object - refering to an ensemble of bagged trees

### Usage

```
## S4 method for signature 'abmodel'
predict(object, newdata)
```

### Arguments

|                      |   |
|----------------------|---|
| <code>object</code>  | A <b>abmodel-class</b> object.              |
| <code>newdata</code> | New data to predict using an abmodel object |

### Value

predictions produced by an abmodel model.

### See Also

[abmodel-class](#) for details about the bagging model;

---

ReadDF

*FUNCTION TO TRANSFORM DATA FRAME INTO LIST WITH GSI REQUIREMENTS*

---

### Description

FUNCTION TO TRANSFORM DATA FRAME INTO LIST WITH GSI REQUIREMENTS

### Usage

```
ReadDF(dat)
```

### Arguments

|                  |            |
|------------------|------------|
| <code>dat</code> | data frame |
|------------------|------------|

### Value

a list containing components that describe the names (see ReadAttrsInfo) and the data (see ReadData) files

THIS FUNCTION HAS TO BE BASED IN READATTRSINFO AND READDATA

---

SymbAttrs

*Retrieve names of symbolic attributes (not including the target)*

---

### Description

Retrieve names of symbolic attributes (not including the target)

### Usage

`SymbAttrs(dataset)`

### Arguments

`dataset` structure describing the data set, according to `read_data.R`

### Value

list of strings

### See Also

`read_data.R`

---

sysdata

*sysdata*

---

### Description

Meta data needed to run the **autoBagging** method.

### Usage

`sysdata`

### Format

a list comprising the following information

**avgRankMatrix** the average rank data regarding each bagging workflow

**workflows** metadata on the bagging workflows

**MaxMinMetafeatures** range data on each metafeature

**metafeatures** names and values of each metafeatures used to describe the datasets

**metamodel** the xgboost ranking metamodel

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